

Markov Random Fields

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НАЦИОНАЛЬНЫЙ ИССЛЕДОВАТЕЛЬСКИЙ
УНИВЕРСИТЕТ

Conditional probabilities

- Joint probability distribution

$$P(x_0, \dots, x_n) = P(X_0 = x_0, \dots, X_n = x_n) = P(\mathbf{x})$$

random variable X_i takes value x_i

- Chain rule

$$P(x_0, \dots, x_n) = P(x_0)P(x_1|x_0)P(x_2|x_1, x_0)\dots = P(x_0) \prod_{i=1}^n P(x_i|x_0, \dots, x_{i-1})$$

- Markov property

$$P(x_0, \dots, x_n) = P(x_0)P(x_1|x_0)P(x_2|x_1)\dots = P(x_0) \prod_{i=1}^n P(x_i|x_{i-1})$$

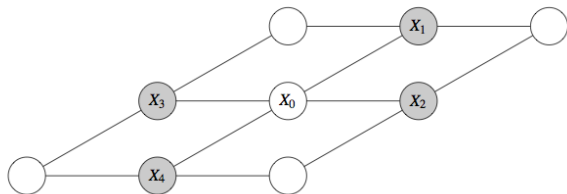
- Independent variables

$$P(x_0, \dots, x_n) = P(x_0)P(x_1)P(x_2)\dots = \prod_{i=0}^n P(x_i)$$

- A Markov random field is set of random variables X_i on the finite set of sites $S = \{1..N\}$ (lattice/network) with probability function satisfying Markovian property relative to the neighborhood

$$P(X_i = x_i | X_j = x_j, j \neq i) = P(X_i = x_i | X_j = x_j, j \in \mathcal{N}(i))$$

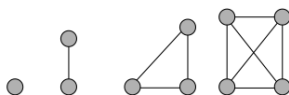
- Undirected graphical model: nodes represent variables, edges represent the dependence structure between random variables
- Markov network represents joint probability distribution
- Only neighboring sites interact with each other (local Markov property)



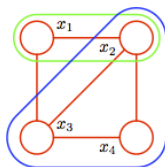
$$\mathcal{N}(X_0) = \{X_1, X_2, X_3, X_4\}$$

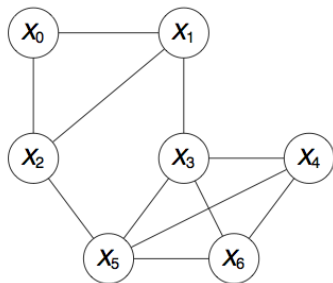
Cliques and maximal cliques

A clique of a graph is its complete subgraph



A maximal clique is a clique that is not a subset of another clique (can not be extended by adding another vertex)





$\{X_0, X_1, X_2\}, \{X_1, X_3\}, \{X_2, X_5\}, \{X_3, X_4, X_5, X_6\}$

Click factorization

Probability distribution factorizes with respect to a given undirected graph if it can be written as

$$P(X) = \frac{1}{Z} \prod_{c \in \mathcal{C}} \psi_c(x_c)$$

\mathcal{C} - set of maximal cliques, c -maximal clique

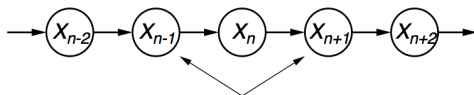
ψ_c - factor potentials / clique potentials, real valued function

Z - normalization factor, partition function

$$Z = \sum_{x \in X} \prod_{c \in \mathcal{C}} \psi_c(x_c)$$

if $V_c(x) = -\log \psi_c(x)$

$$P(X) = \frac{1}{Z} e^{-\sum_{c \in \mathcal{C}} V_c(x_c)}$$



- neighbours $n - 1, n + 1$
- cliques = pairs
- Joint probability

$$P(x) = P(x_0) \prod_{n=1}^N P(x_n | x_{n-1}) = P(x_0) \exp \left\{ \sum_{n=1}^N \log P(x_n | x_{n-1}) \right\}$$

- Potential $V(x_n, x_{n-1}) = -\log P(x_n | x_{n-1})$

- Gibbs distribution (measure)

$$P(X) = \frac{1}{Z} e^{-\beta U(x)}$$

$U(x)$ - energy function, β - spatial smoothness parameter

- partition function

$$Z = \sum_x e^{-\beta U(x)}$$

- In statistical mechanics $\beta = 1/kT$, inverse temperature
- Boltzman distribution

Ising Model

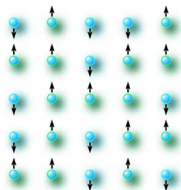
- Classical model of magnetism (1D model solved by Ernst Ising in 1925)
- one or two-dimensional lattices, spin takes values $\sigma_i = \pm 1$
-

$$U = -J \sum_{\langle i,j \rangle} \sigma_i \sigma_j - H \sum_i \sigma_i$$

- Configuration probability

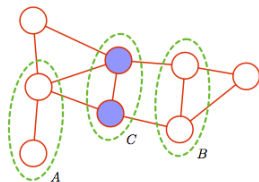
$$P(\sigma) = \frac{1}{Z} e^{-\beta U}$$

- $J > 0$ - ferromagnetic, $J < 0$ - antiferromagnetic



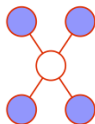
Graph separation

In an undirected graph with disjoint subsets of nodes \mathcal{A} , \mathcal{B} , \mathcal{C} if every path from \mathcal{A} to \mathcal{B} includes at least one node from \mathcal{C} , then \mathcal{C} separates \mathcal{A} from \mathcal{B} .



Markov blanket

- Markov blanket of a node is the (minimal) set of variables making the given node independent of all the remaining nodes in the model;
- The local Markov property referred to in the Hammersley-Clifford theorem states that the neighbors of a node in a Markov random field are a Markov blanket of that node in the graph. That is, $MB(X_i) = N(X_i)$;



Hammersley - Clifford theorem

Given random vector X and undirected graph with positive probability distribution $P(X) > 0$ for any realization of X , the following conditions are equivalent:

- $P(X)$ is a Gibbs distribution that factorizes according to the maximal cliques in the graph
- local Markov property:
$$P(X_i = x_i | X_j = x_j, j \neq i) = P(X_i = x_i | X_j = x_j, j \in \mathcal{N}(i))$$
- global Markov property:
If \mathcal{A} , \mathcal{B} , \mathcal{C} are three disjoint subsets of X and \mathcal{C} separates \mathcal{A} from \mathcal{B} , then $P(\mathcal{A} | \mathcal{B}, \mathcal{C}) = P(\mathcal{A} | \mathcal{C})$

Log-linear model

- Any MRF can be written as log-linear model (logistics model)
- For each state of each maximal clique introduce $f(X_c) = \{0, 1\}$
- Potential function

$$\psi_c(x_c) = \exp \left\{ \sum_{j=1}^{m_c} w_j f_j(x_c) \right\}$$

m_c number of features in the clique

$$P(x) = \frac{1}{z} \prod_C \exp \left\{ \sum_{j=1}^{m_c} w_j f_j(x_c) \right\} = \frac{1}{z} \exp \left\{ \sum_C \sum_{j=1}^{m_c} w_j f_j(x_c) \right\}$$