

Simulated annealing and Gibbs sampler

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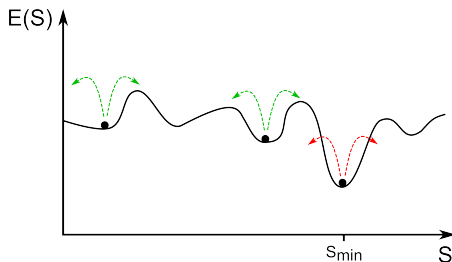
12.12.2013



НАЦИОНАЛЬНЫЙ ИССЛЕДОВАТЕЛЬСКИЙ
УНИВЕРСИТЕТ

Simulated annealing

- Global optimization method (vs greedy strategies - local minimum)
- Works for both continuous and discrete optimization problems
- Intuition from thermodynamics, physical annealing process
- Algorithm:
 - 1 generate trial point and evaluate function at that location.
 - 2 accept new location if it reduces "energy"(improves solution)
 - 3 accept some new location even not improving the solution
 - 4 probability accepting non-improving location decreases with lowering "temperture"



- Compute change of energy for a k -step $\Delta E_k = E_k - E_{k-1}$:
 - If $\Delta E_k \leq 0$, accept the step
 - if $\Delta E_k > 0$, accept the step with probability $P(\Delta E_k) = e^{-\Delta E_k / T_k}$
- Cooling schedule:
 - $T_k = \alpha T_0 / k$
 - $T_k = \alpha T_0 / \log k$
 - $T_k = T_0 / \alpha^k$

Traveling salesman problem

Travelling salesman problem: given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city exactly once and returns to the origin city? (NP-hard problem in combinatorial optimization)

Simulated annealing algorithm:

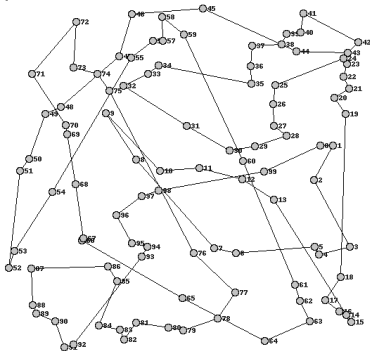
- Define energy cost function:

$$E = \sum_i^N \sqrt{(x_{i+1} - x_i)^2 + (y_{i+1} - y_i)^2}$$

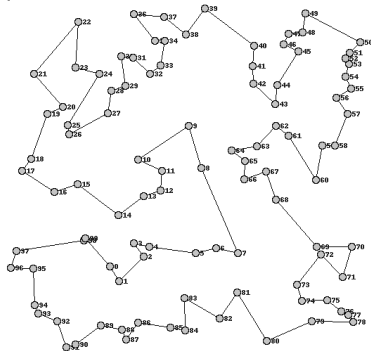
- Select initial route (sequence of city labels)
- Iteratively improve the route by trying local changes:
swap a pair of cities + reverse the section between them
- always accept lower energy swap, sometimes higher energy
- reduce temperature with cooling schedule

Traveling salesman problem

city100.txt: -6451.121265



city100.txt: -4039.860428



- MCMC constructs Markov chain that generates random samples distributed according to $P(x)$
- Metropolis algorithm uses symmetric "candidate" distribution $Q(x, x^*) = Q(x^*, x)$
- Probability of "forward move" of the chain:

$$\alpha(x, x^*) = \min \left[1, \frac{P(x^*)}{P(x)} \right]$$

- Consider Boltzman (Gibbs) distribution

$$P(x) = \frac{1}{Z} e^{-\frac{E(x)}{T}}$$

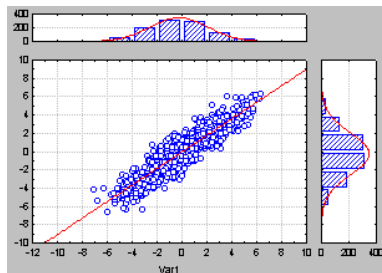
- Probability of move

$$\alpha(x, x^*) = \min \left[1, e^{-\frac{E(x^*) - E(x)}{T}} \right] = \min \left[1, e^{-\frac{\Delta E}{T}} \right]$$

$\Delta E \leq 0$ - always move, $\Delta E > 0$ move with probability $\exp\left(-\frac{\Delta E}{T}\right)$

The Gibbs sampler

- Goal: get random samples from joint multivariate density $p(x_1, \dots, x_n)$ if it is not known explicitly or hard to sample from
- Given conditional univariate distributions $p(x_1|x_2 \dots x_n)$, $p(x_2|x_1 \dots x_n)$, .. $p(x_n|x_1 \dots x_{n-1})$



- Bayesian inference, posterior distributions
- Approximate joint distribution (histogram), compute averages

- joint bivariate distribution

$$p(x, y)$$

- marginal distribution

$$p(x) = \int p(x, y) dy$$

$$p(y) = \int p(x, y) dx$$

- conditional probability

$$p(x|y) = p(x, y)/p(y)$$

$$p(y|x) = p(x, y)/p(x)$$

- marginal from conditional distribution

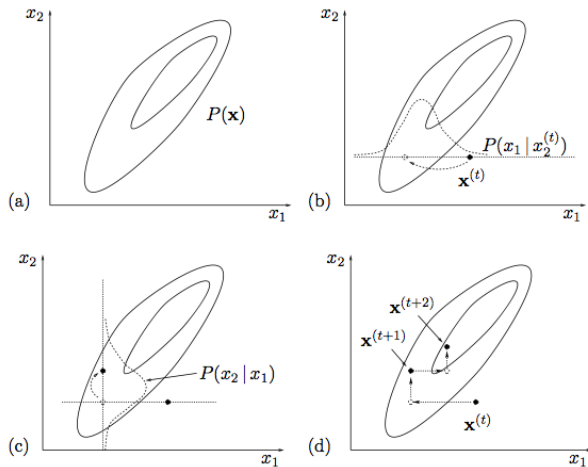
$$p(x) = \int p(x|y)p(y)dy = E_{p(y)}[p(x|y)]$$

$$p(y) = \int p(y|x)p(x)dx = E_{p(x)}[p(y|x)]$$

Gibbs sampler: bivariate case

- Given: $p(x|y), p(y|x)$
- Choose $y_0, t = 0$
- do "sampler scan"
 - $x_t \sim p(x|y = y_t)$
 - $y_{t+1} \sim p(y|x = x_t)$
- repeat k -times, Gibbs sequence $(x_0, y_0), (x_1, y_1) \dots (x_k, y_k)$

Gibbs sampler



Algorithm: Gibbs sampler

Input: all marginals $p(x_i | x_1 \dots x_{i-1}, x_{i+1}, \dots, x_n)$

initialize $\mathbf{x}^{(0)} = (x_1^{(0)}, \dots, x_n^{(0)})$, $t = 0$

while $t < T$ **do**

for $i = 1$ to n **do**

$x_i^{(t+1)} \sim p(x_i | x_1^{(t+1)}, \dots, x_{i-1}^{(t+1)}, x_{i+1}^{(t)}, \dots, x_n^{(t)})$

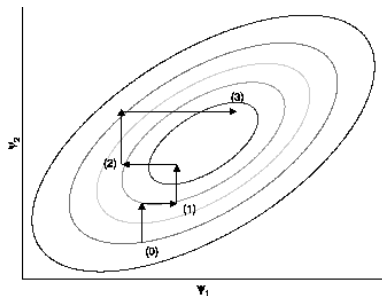
end

$t = t + 1$

end

return $\{\mathbf{x}^0, \mathbf{x}^1, \dots, \mathbf{x}^N\}$

Gibbs sampler



- Metropolis-Hastings

$$\alpha(x, x^*) = \min \left[1, \frac{p(x^*)Q(x|x^*)}{p(x)Q(x^*|x)} \right]$$

- use conditional $p(x|x^*)$ as a candidate density $Q(x|x^*)$
 $(x^t, y^t) \rightarrow (x^{t+1}, y^t)$

$$\alpha = \frac{p(x^{t+1}, y^t)p(x^t|y^t)}{p(x^t, y^t)p(x^{t+1}|y^t)} = \frac{p(x^{t+1}, y^t)}{p(x^t, y^t)} \frac{p(x^t, y^t)}{p(y^t)} \frac{p(y^t)}{p(x^{t+1}, y^t)} = 1$$

- MCMC algorithm with acceptance probability 1

- Explaining the Gibbs Sampler. G. Casella, E.I. George. The American Statistician, V 46, N3, 1992, pp 167-174
- Markov Chain Monte Carlo and Gibbs Sampling. Lecture notes. B. Walsh
- Introduction to Monte Carlo methods. Notes. D.J.C. Mackay.