Social learning

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Structural Analysis and Visualization of Networks



1 Social learning

2 Reaching consensus• DeGroot model

Social influence networks

- Social learning is changing ones behavior or beliefs based on direct observation of others (imitation, aggregation, adoptation)
- Local interactions (network)
- Information is dispersed through the network
- No centralized mechanism for information aggregation

"Reaching a consensus", Morris DeGroot 1974

Consensus - mutual agreement on a subject among group of people

- Group of people with opinions on the subject
- Can a common belief be reached?
- How long would it take?
- How each individual belief contribute to consensus?
- Which individuals have the most influence over final beliefs?

- Opinion $p_i(t) \in [0..1]$,
- Initial opinion on the subject $p_i(0)$
- T_{ij} is weight on the opinion of others, $i \to j$, how much i "listens to opnion" of j, $\sum_j T_{ij} = 1$
- Opinion update

$$p_i(t+1) = \sum_j T_{ij} p_j(t)$$

• Could a consensus be reached, i.e. all opinions converge to the same value?

$$\lim_{t\to\infty}p_i(t)=p^\infty$$

Example 1



$$T = egin{pmatrix} 1/3 & 1/3 & 1/3 \ 1/2 & 1/2 & 0 \ 0 & 1/4 & 3/4 \end{pmatrix}$$

Example 1

Initial beliefs

$$p(0) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Updating

$$p(1) = Tp(0) = \begin{pmatrix} 1/3 & 1/3 & 1/3 \\ 1/2 & 1/2 & 0 \\ 0 & 1/4 & 3/4 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1/3 \\ 1/2 \\ 0 \end{pmatrix}$$
$$p(2) = Tp(1) = \begin{pmatrix} 1/3 & 1/3 & 1/3 \\ 1/2 & 1/2 & 0 \\ 0 & 1/4 & 3/4 \end{pmatrix} \begin{pmatrix} 1/3 \\ 1/2 \\ 0 \end{pmatrix} = \begin{pmatrix} 5/18 \\ 5/12 \\ 1/8 \end{pmatrix}$$

Consensus

$$p(20) = Tp(19) = \begin{pmatrix} 3/11 \\ 3/11 \\ 3/11 \end{pmatrix}$$
$$p(21) = Tp(20) = p(20)$$



$$T = \begin{pmatrix} 0 & 1/2 & 1/2 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

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Example 2

Initial beliefs

$$p(0) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Updating

$$p(1) = Tp(0) = \begin{pmatrix} 0 & 1/2 & 1/2 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$
$$p(2) = Tp(1) = \begin{pmatrix} 0 & 1/2 & 1/2 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Consensus

$$\nexists \lim_{t\to\infty} T^t p(0)$$

Perron - Frobenius Theorem

Perron & Frobenius, 1912, linear algebra. For stochastic matrices $\sum_{j} T_{ij} = 1$:

Theorem

Let **T** be a square 1) non-negative $T_{ij} \ge 0$, 2) irreducible, 3) aperiodic stochastic matrix. Then there are exist

$$\lim_{t\to\infty}T_{ij}^t=\pi_j$$

where

$$\pi_j = \sum_i \pi_i T_{ij}$$

 $\pi = (\pi_1, \pi_2, ... \pi_n)$ - is the left eigenvalue of **T**, corresponding to $\lambda_1 = 1$ and $\sum_i \pi_i = 1$

Irreducible matrix - strongly connected graph Aperiodic matrix - the greatest common divisor of the length of the cycles in the associated graph is gcd = 1Leonid E. Zhukov (HSE) Lecture 16 12.05.2015

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Limiting belief

• Limiting belief

$$p(t) = Tp(t-1) = T^{2}p(t-2) = T^{t}p(0)$$

$$p^{\infty} = \lim_{t \to \infty} p(t) = \lim_{t \to \infty} T^{t}p(0)$$

$$\lim_{t \to \infty} T^{t} = \lim_{t \to \infty} \begin{pmatrix} T_{11} & \dots & T_{1n} \\ \dots & \dots & \dots \\ T_{n1} & \dots & T_{nn} \end{pmatrix}^{t} = \begin{pmatrix} \pi_{1} & \pi_{2} & \dots & \pi_{n} \\ \pi_{1} & \pi_{2} & \dots & \pi_{n} \\ \pi_{1} & \pi_{2} & \dots & \pi_{n} \end{pmatrix}$$

$$\mathbf{p}^{\infty} = \begin{pmatrix} \pi_{1} & \pi_{2} & \dots & \pi_{n} \\ \pi_{1} & \pi_{2} & \dots & \pi_{n} \\ \pi_{1} & \pi_{2} & \dots & \pi_{n} \end{pmatrix} \begin{pmatrix} p_{1}(0) \\ \dots \\ p_{n}(0) \end{pmatrix} = \begin{pmatrix} p^{\infty} \\ \dots \\ p^{\infty} \end{pmatrix}$$

• Left eigenvector

$$\pi \mathbf{T} = \pi \lambda$$

• Example 1

$$T^{20} = \begin{pmatrix} 1/3 & 1/3 & 1/3 \\ 1/2 & 1/2 & 0 \\ 0 & 1/4 & 3/4 \end{pmatrix}^{20} = \begin{pmatrix} 0.27 & 0.36 & 0.36 \\ 0.27 & 0.36 & 0.36 \\ 0.27 & 0.36 & 0.36 \\ 0.27 & 0.36 & 0.36 \\ 0.27 & 0.36 & 0.36 \\ 0.27 & 0.36 & 0.36 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0.27 \\ 0.27 \\ 0.27 \\ 0.27 \\ 0.27 \end{pmatrix}$$

• Left eigenvector

$$\pi \mathbf{T} = \pi \lambda$$

$$\lambda = \{1, 0.5, 0.083\}, \quad \pi_1 = (0.27, 0.36, 0.36)$$

Social influence

• Limiting belief

$$p^{\infty} = \lim_{t \to \infty} T^t p(0) = \prod p(0) = \sum_i \pi_i p_i(0)$$

• Influence vector

$$\pi = (\pi_1, \pi_2, ..\pi_n)$$



$$\pi = (0.27, 0.36, 0.36)$$

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Social influence

Equal weights on edges, A_{ij} - adjacency matrix, d_i - node out-degree



• Opinion updates:

$$p_i = \sum_j T_{ij} p_j = \sum_j rac{A_{ij}}{d_i} p_j$$
 $p = (D^{-1}A)p$

Random walk (PageRank)

$$r_{i} = \sum_{j} P_{ji}r_{j} = \sum_{j} \frac{A_{ji}}{d_{j}}r_{j}$$
$$r = r(D^{-1}A)$$

Closed sets

 A set of nodes C is called a *closed set* if there is no direct link from the node in C to the node outside C (there is no i ∈ C and j ∉ C such that T_{ij} > 0)



- *T* is convergent if and only if every set of nodes that is strongly connected and closed is aperiodic
- Every strongly connected closed and aperiodic set will reach own consensus

• Time-varying updates:

$$p(t) = \left[(1 - \lambda(t))I + \lambda(t)\hat{T}
ight] p(t-1)$$

DeMarzo, Vayanos, Zwibel, 2003

Similar beliefs:

$$T_{ij}(p(t)) = \begin{cases} \frac{1}{n_i(p(t))}, & |p_i(t) - p_j(t)| < d, n_i = \#\{k : |p_i - p_k| < d\} \\ 0, & otherwise \end{cases}$$

Krause

Close beliefs:

$$T_{ij}(p(t)) = \frac{e^{-\gamma_{ij}|p_i(t)-p_j(t)|}}{\sum_k e^{-\gamma_{ik}|p_i(t)-p_k(t)|}}$$

• Under some conditions consensus could be reached in all models

Wisdom of the crowd

- Wisdom of crowd taking into account collective opinion of a group of individuals for collective decision
- Claim: collective decision is better that decision by any individual due to independent judgements and aggregation process that removes random noise and averages out decisions.
- Will consensus converge to "correct" values?
- Opinion leader



Noah Friedkin 1991, ..,1999

- interpersonal influence for collective decisions
- modifying attitudes and opinions by interaction
- influence process in a group of N actors:

$$\mathbf{y}(t) = \mathbf{DTy}(t-1) + (\mathbf{I} - \mathbf{D})\mathbf{y}(0)$$

 $\mathbf{y}(t)$ - vector of actors' opinion at time t $\mathbf{y}(0)$ - vector of actors' initial opinion \mathbf{T} - N × N matrix of interpersonal influence $\mathbf{D} = diag(d_{11}, ..., d_{NN})$ - matrix of actors' susceptibilities to interpersonal influence • Assuming the process reaches an equilibrium, $\mathit{lim}_{t
ightarrow \mathbf{y}}(t) = \mathbf{y}^\infty$

$$\mathbf{y}^{\infty} = \mathbf{D}\mathbf{T}\mathbf{y}^{\infty} + (\mathbf{I} - \mathbf{D})\mathbf{y}(0)$$

Solution:

$$\mathbf{y}^\infty = (\mathbf{I} - \mathbf{D}\mathbf{T})^{-1}(\mathbf{I} - \mathbf{T})\mathbf{y}(0)$$

• Limiting beliefs (no consensus):

$$\mathbf{y}^{\infty} = \begin{pmatrix} y_1^{\infty} \\ y_2^{\infty} \\ \dots \\ y_n^{\infty} \end{pmatrix}$$

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