Spatial Model of Segregation

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Spatial model of segregation

"Dynamic Models of Segregation", Thomas Schelling, 1971

- Micro-motives and macro-behavior
- Personal preferences lead to collective actions
- Global patterns of spatial segregation from homophily at a local level
- Segregated race, ethnicity, native language, income
- Cities are strongly racially segregated. Are people that racists?
- Agent based modeling: agents, rules (dynamics), aggregation
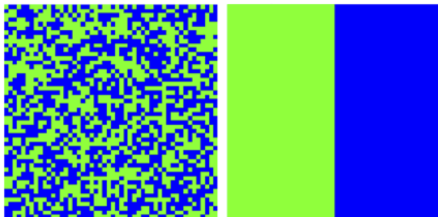
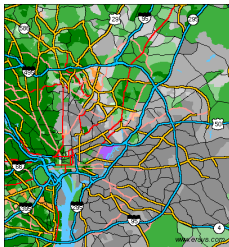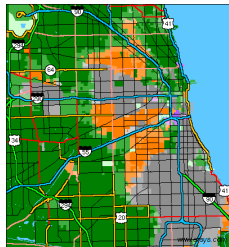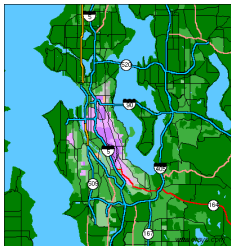Integrated pattern   Segregated pattern

New York

Washington

Chicago

Seattle
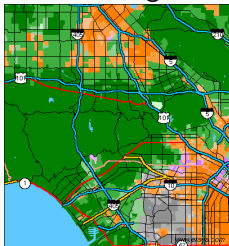
Los Angeles
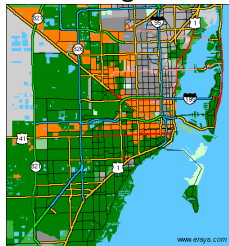
Miami

2012 US Presidential Elections Map

TOP CANDIDATE'S SHARE OF VOTE   OBAMA   40% 50 60 70%   ROMNEY   40% 50 60 70%
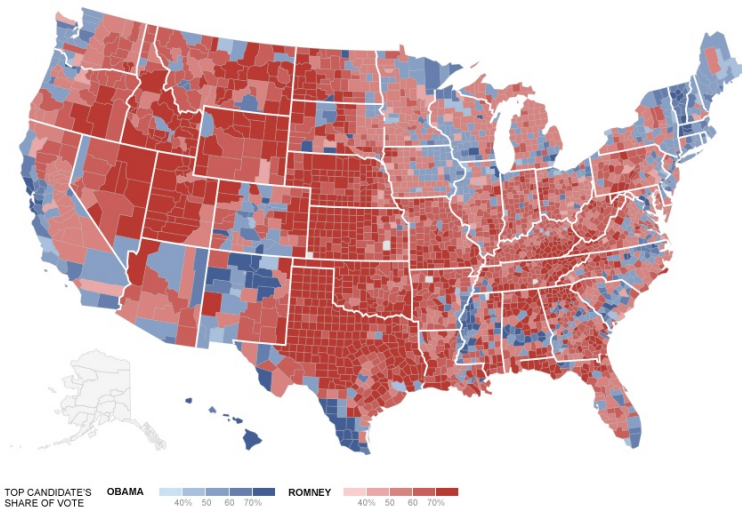
Schelling's model of segregation

- Population consists of 2 types of agents
- Agent reside in the cells of the grid (2-dimensional geography of a city), 8 neighbors
- Some cells contain agents, some unpopulated
- Every agent wants to have at least some fraction of agents (threshold) of his type as neighbor (satisfied agent)
- On every round every unsatisfied agent moves to a satisfactory empty cell.
- Continues until everyone is satisfied or can't move

satisfied agent   unsatisfied agent

- preference threshold $\lambda = 3/7$
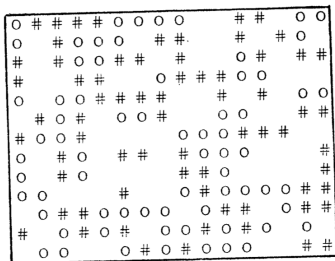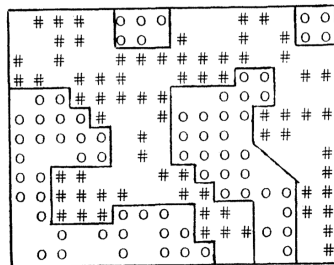
Fig.7   Fig.10

T. Schelling, 1971

Model

- N - nodes, θ - fraction of occupied by A and B

$$n_A + n_B = \theta \cdot N$$

- Proportion of "unlike" nearest neighbors, $k_i = \#NN$

$$P_i = \left\{ \begin{array}{l} \#n_B/k_i, \text{if } i \in A \\ \#n_A/k_i, \text{if } i \in B \end{array} \right.$$
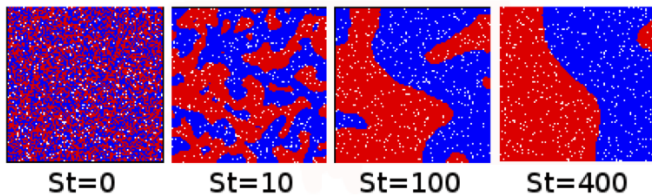
- Utility function, λ - sensitivity (tolerance threshold) level

$$u_i = \left\{ \begin{array}{l} 1, \text{if } P_i \leq \lambda \\ 0, \text{if } P_i > \lambda \end{array} \right.$$
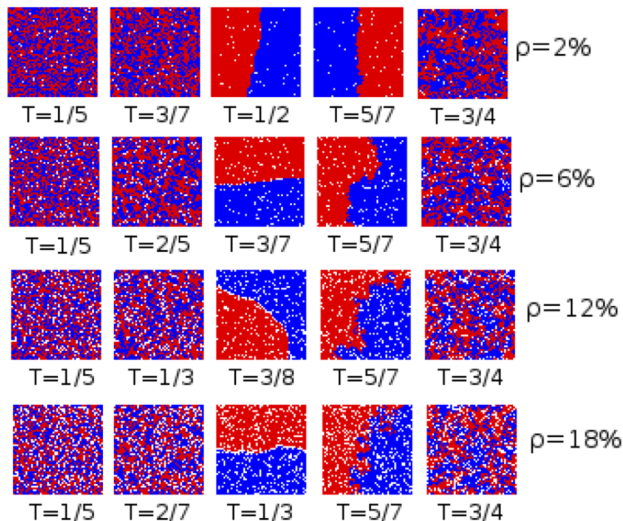
- Every node moves to maximize its utility

Spatial segregation

vacancy 5%, tolerance $\lambda = 0.5$

St=0   St=10   St=100   St=400

L. Gauvin et.al. 2009

Spatial segregation

L. Gauvin et.al. 2009

Algorithm

- time steps $1..T$
- At every time step randomly select an agent, compute utility
- If utility is $u = 0$ move to an empty location to maximize utility
- Movements: 1) random location 2) nearest available location
- Repeat until either all utilities are maximized $\sum_i u_i = \theta N$
  or reaches "frozen" state, no place to move, then $\sum_i u_i < \theta N$
- Total utility of society

$$U = \sum_i u_i$$

Measuring segregation

- Schilling's solid mixing index

$$M = \frac{1}{n_A + n_B} \sum_i P_i$$

- Freeman's segregation index

$$F = 1 - \frac{e^*}{E(e^*)}$$

$e^* = \frac{e_{AB}}{(e_{AB} + e_{AA} + e_{BB})}$ - observed proportion of between group ties,
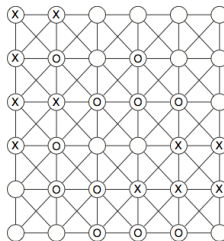$E(e^*) = \frac{2n_A n_B}{(n_A + n_B)(n_A + n_B - 1)}$ - expected proportion for random ties

- Assortative mixing

$$Q = \frac{1}{2m} \sum_{ij} (A_{ij} - \frac{k_i k_j}{2m}) \delta(c_i, c_j)$$
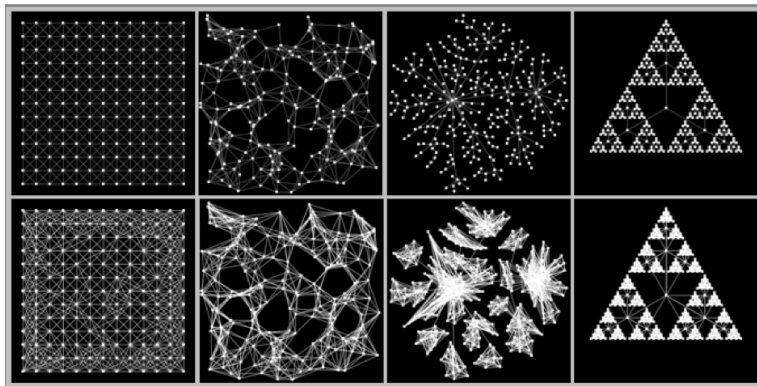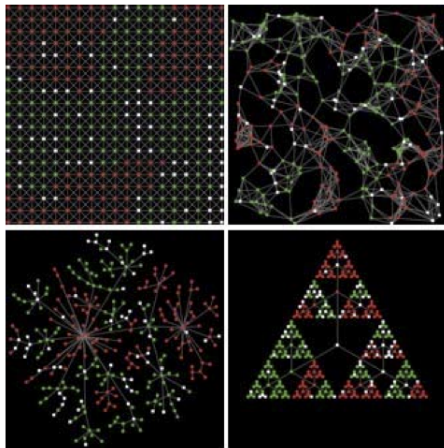
(a) (b)

Spatial segregation on networks

Fixed degree $k = 10$ neighboring graphs: regular, random, scale-free, fractal

Arnaud Banos, 2010

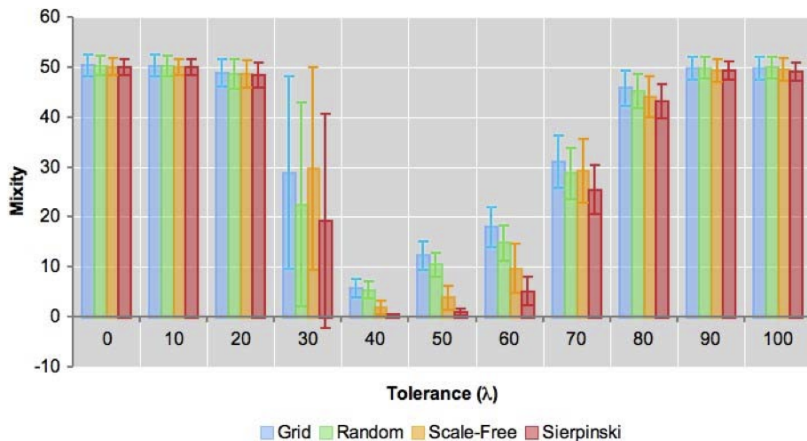# Spatial segregation on networks
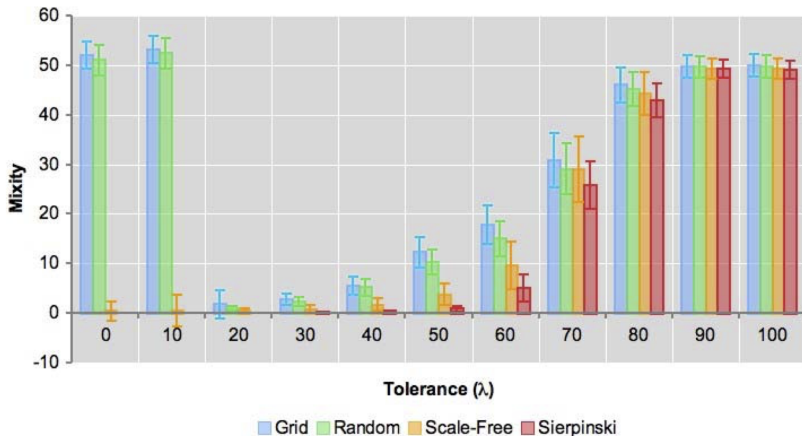
$\lambda = 0.5, \theta = 0.8$

Banos, 2010

Spatial segregation on networks

Banos, 2010

Spatial segregation on networks

$\nu = 10\%$ of random "noise" added for decision to avoid freezes

Banos, 2010

Summary

- Spatial segregation is taking place even though no individual agent is actively seeking it (minor preferences, high tolerance)
- Network structure does affect segregation
- Fixed characteristics (race) can become correlated with mutable (location)

References

- Dynamic Models of Segregation, Thomas C. Schelling, 1971
- Segregation in Social Networks, Linton Freeman, 1978
- Gauvin L, Vannimenus J, Nadal JP. Phase diagram of a Schelling segregation model. The European Physical Journal B, 70:293-304, 2009
- Arnaud Banos. Network effects in Schelling's model of segregation: new evidences from agent-based simulations. 2010

Module summary

1. Diffusion on network
2. Epidemics on networks
3. Social contagion and spread of information
4. Diffusion of innovation and influence maximization
5. Label propagation on graph
6. Link prediction
7. Social learning
8. Spatial segregation